

HAND SPIN WHEEL BALANCER

EEWB330B



OPERATION INSTRUCTIONS

MODE D'EMPLOI MANUAL DE OPERADOR

The off-the-vehicle wheel balancer is designed for dynamic and static balancing of passenger car and light-truck and motorcycles wheels, that fall within the limits stated in the technical specifications. This is a high accuracy measuring device. Handle with care.





IMPORTANT SAFETY INSTRUCTIONS





• Basic safety precautions should always be followed.

and all parts of your body away from moving parts.

Wear safety goggles.

Read and follow all Instructions and safety messages.

Wear appropriate clothing; keep hair and loose fitting clothing, your hands



Eye injury or other bodily injury can result from flying particles or entanglement with moving parts.

• Electric powered wheel balancer can cause shocks, fire or explosion.



Do not operate the wheel balancer with a damaged power cord or plug.

Do not use on wet surfaces, outdoors or expose the balancer to rain.

Unplug the power cord when the balancer is not in use.



If an extension cord is used, make sure that it is in good condition and that the current rating is 8 Amps or higher.

Use only in well ventilated areas.

Do not operate the balancer in the vicinity of flammable liquids (gasoline) or below grade or in an explosive atmosphere.



Electric shock, fire or explosion can cause serious injury or death.

• Misuse of this wheel balancer can result in accidents.

Do not allow untrained or unauthorized personnel to operate the balancer.

Do not disable or bypass the hood safety interlock system.

Always securely tighten the quick nut that holds the wheel in place during the mounting procedure.

Improperly balanced wheels can cause damage to the vehicle or automotive accidents. Personal injury can result from alteration to the balancer or improper use.

Suppon

Table of Contents

	Safety Instructions	3
1.0	Introduction	5
1.1	Safety Notice	5
1.2	Balancer Application	5
1.3	EEWB330B Specifications	6
1.4	Features	6
15	Standard Accessories	7
1.6	Ontional Accessories	7
1.0	Dimensions of The Machine	. <i>i</i>
1.7	Required Installation Area	U
1.0	Installation Installation Area	. U
1.9	Delenser Installation	0
2.0	Dalahuer Installation	9
2.2		9
3.0		10
3.1		10
3.2		.11
4.0	Operation of The Balancer	12
4.1	Check List - Inspection	12
4.2	Wheel Mounting	12
4.2.1	Standard Wheels (Back Cone Mount)	12
4.2.2	Centering Light-Truck Wheels	13
4.2.3	Wheel Mounting Requiring Special Tooling	13
4.3	Mode Selection	13
4.3.1	Weight Placement Modes	14
4.3.2	Motorcycle Mode	14
4.3.3	SAPE Arm positioning for Alu weights placement	15
4.4	Selecting Operator Preferences	16
4.4.1	Fine Balancing Mode	16
4.4.2	Ounce/Grams Conversion	16
443	Rim Diameter In Millimeters	16
4 5	Enter Rim Parameters	16
4.5.1	Rim Distance (offset)	16
4.5.2	Mensure/Enter rim width	16
4.5.2	Manual Darameter Entry	17
4.5.5	Manual Dim Diamatar Entry	17
4.5.3.1	Manual Rim Diameter Entry	17
4.5.3.2		17
4.6	Easy Alu Function	17
4.6.1	Automatic rim Dimension reading and Alu P Mode Selection	1/
4.7	Spinning the Wheel	18
5.0	Correction of The Imbalance	18
5.1	Alu P Weights Application with the SAPE Arm	19
6.0	Spoke Balancing Mode	20
6.1	Split Weight Mode (SWM)	20
7.0	User Calibration	21
8.0	User Functions	22
8.1	Data Recall	22
8.2	Weight Unit Toggle Mode	23
8.3	Dimension Unit Toggle Mode	23
9.0	Optimization/Weight Minimization.	24
10.0	Trouble Shooting	32
10.1	System Messages	33
10.1.1	C Codes	33
10.1.2	E Codes	35
10 1 3	H Codes - Warning	37
11 0	Maintenance	37
	Warranty/Service and Repair	38
	Transing, control and repair	50



1.0 INTRODUCTION

Congratulations on purchasing the **EEWB330B** computer wheel balancer. This wheel balancer is designed for ease of operation, accuracy, reliability and speed. With a minimum of maintenance and care your wheel balancer will provide many years of trouble-free operation.

Instructions on use, maintenance and operational requirements of the machine are covered in this manual.

STORE THIS MANUAL IN A SAFE PLACE FOR FUTURE REFERENCE. READ THIS MANUAL THOROUGHLY BEFORE USING THE MACHINE.

1.1 SAFETY NOTICE

This manual is a part of the balancer product.

Read carefully all warnings and instructions of this manual since they provide important information concerning safety and maintenance.

1.2 BALANCER APPLICATION

The Snap-on wheel balancer model **EEWB330B** is intended to be used as equipment to balance car, light truck and motorcycles wheels within the following range:

Maximum wheel diameter	:	42" (1067mm)
Maximum wheel width	:	20" (508mm)
Maximum wheel weight	:	120 lbs / 54 kg

This equipment is to be only used in the application for which it is specifically designed. Any other use shall be considered as improper and abusive.

The manufacturer shall not be considered liable for possible damages caused by improper, wrong, or abusive use of this equipment.

SIEDER

1.3 EEWB330B SPECIFICATIONS

Digital wheel balancer for car, light truck and motor-cycles wheels.

Weight Imbalance Accuracy	0.10 oz. / 2.8 grams				
Weight Placement Resolutio	n ± 0.7 degrees				
Weight Imbalance Resolution:					
Roundoff Mode	0.25 oz. / 5 grams				
Non-Roundoff Mode	0.05 oz. / 1 gram				
Max. Shaft Weight Capacity	120 lbs / 54 kg				
Max.Tire Diameter	42" / 1067 mm				
Rim Width Capacity	3"-20" / 76 mm - 508 mm				
Rim Diameter Capacity	8"-32" / 203 mm-812 mm				
Balancing Cycle Time.	6-10 seconds				
Shaft Speed at calculation	90 RPM				
Electrical Requirements	115vac, 1ph, 60Hz, 2A				
Required Work Area 100	" x 67" (2540 x1702 mm)				

Shipping Weight, complete	325 lbs/147 kg
Shipping Dimensions	52.75"h 41.5"w 37"d
Machine Dimensions	54"h 51"w 48.5"d
Actual Weight with Accessories	309 lbs / 140 kg
Operating Temperature Range	32-122F / 0-50C

1.4 FEATURES

ACCURACY

- Weight placement accuracy is ± 0.7°
- Weight imbalance accuracy to 2.8 grams
- Self test check with every power up cycle
- Fast operator calibration
- Pre-programmed Error Codes indicate procedural errors or safety concerns

SPEED and DURABILITY

- Automatic distance and diameter entry. Simply touch the SAPE Arm to the wheel, the distance and diameter parameters are automatically entered
- Quick clamp speed nut reduces wheel mounting time
- Captured back spring eliminates having to handle the backing spring
- Quick cycle time of 6 to 10 seconds
- Automatic recalculation if weight positions are changed. No need for re-spinning the wheel
- Common 40 mm diameter mounting shaft
- Weight pocket storage tray
- Easy-to-Read Data display
- Easy weight tray access

SOFTWARE VERSATILITY

- Both dual weight Dynamic and single weight Static capability
- Match Balance program for reducing weight required
- Built-in spin counter for monitoring balancer productivity
- Service code access to all Balancer electronic functions for fast, easy diagnosis
- Operator selectable round-off mode
- Easy Alu enter the rim dimensions and automatically select a balancing mode
- 5 Aluminum Modes
 - 2 Alu-S modes
 - Hidden Weight (Spoke) mode
- Ounce / Gram toggle from front panel
- Multiple operator feature allows several operators to recall wheel parameters





1.5 STANDARD ACCESSORIES

Standard accessories (Figures 1, 2, and 3,) included with the EEWB330B are:

EAM0003J69A
EAM0005D25A
EAM0005D24A
EAM0005D23A
EAC0058D07A
EAC0058D08A
EAA0263G66A
EAM0005D40A
EAM0021D90A
EAA0247G21A
EAC0060G02A
EAM0006G01A
WWPR13A
EAM0005D34A
EAC0058D15A

Cone, 87-137 mm / 3.4"-5.4" Cone, 96-114 mm / 3.8"-4.5" Cone, 71-99mm /2.8"-3.9" Cone, 40-76mm / 1.6" -3.0" Cup -Pressure Disk -Pressure Quick Nut Weight -Calibration Standard 40mm Stub Shaft Caliper -Rim Width Flange -Cover, Hook Pin -Accessory Weight Pliers Fastening Rod Soft Protector Ring











Figure 1



Figure 2 - Rim width caliper



Figure 3 - Plier

Weight Pliers (Figure 3).

Versatile weight hammer/plier. In addition to hammering on weight and used weight removal, the hammer/ plier can be used to reshape worn weight clips and trim weight to size

1.6 OPTIONAL ACCESSORIES



EEWB3-1A Car, SUV and Lt Truck Pin Plate Set EEWB3-4 9-pc Collet Set EAK0309J20A Stand





EEWB3-5 Spacer

EEWB3-4 9-pc Collet Set



EEWB3-1A Car, SUV and Lt Truck Pin Plate Set

STEDET

PRE-INSTALLATION CONSIDERATIONS 1.7 DIMENSIONS OF THE MACHINE



Figure 4 - Dimensions for the installation.



Figure 5 - Recommended Work Area

1.8 REQUIRED INSTALLATION AREA

Make sure that from the operating position the user can see all of the machine and the surrounding area.

The operator should prevent non authorized persons and/or objects from entering the area which may create potential hazards.

The machine should be installed on a stable level floor. Do not install the machine on a uneven floor.

If the balancer is to be installed on a raised floor, the floor must have a capacity of at least 110lbs per sq ft. (5000 $N/m^2\,$ - 500 kg/m²).

It is not required to secure the machine to the floor.

Install the machine in a dry, covered area.

The installation of the machine requires a working area of at least 60" x 48" (1524mm x 1219 mm) (Figure 5).

NOTE: Do not install the balancer below grade level or in a pit.

1.9 INSTALLATION INSTRUCTIONS

CAUTION! CAREFULLY REMOVE THE BALANCER FROM THE PALLET.

Remove the hardware that secures the machine to the pallet and slide the balancer onto the floor where it is to be installed.

THE UNIT IS HEAVY AND THE WEIGHT IS NOT EVENLY DISTRIBUTED.

DO NOT LIFT THE BALANCER BY THE SHAFT.

DROPPING THE UNIT MAY CAUSE PERSONAL INJURY OR EQUIPMENT DAMAGE.

!!IMPORTANT!!!

Machines are shipped calibrated from the factory. Do not attempt field calibration unless balance results deem calibration as necessary.

SIEDER

2.0 BALANCER INSTALLATION Mounting the Shaft Adapter

IMPORTANT!

CHECK THAT THE SURFACES ARE PERFECTLY CLEAN AND NOT DAMAGED. AN INCORRECT MOUNTING MAY RESULT IN SIGNIFICANT IMBAL-ANCE.

A. Mount the threaded shaft onto the arbor of the balancer. Tighten firmly using supplied rod. (Figure 6).



2.2 ELECTRIC INSTALLATION

ANY ELECTRICAL WIRING MUST BE PER-FORMED BY LICENSED PERSONNEL.

ALL SERVICE MUST BE PERFORMED BY AN AUTHORIZED SERVICE TECHNICIAN.

Check on the plate of the machine that the electrical specifications of the power source are the same as the machine. The machine uses 115VAC, 60Hz, 1Ph, 4.0 Ampere.

NOTE:

Any electrical outlet installation must be verified by a licensed electrician before connecting the balancer.

NOTE:

This machine performs a self-test routine on startup. There will be a delay of several seconds before the display is activated.

Figure 6

B. Install the accessory pins (Figure 7). Tighten firmly.



Figure 7

C. Place cones and other accessories onto the accessory pins.

STEDER

3.0 TERMINOLOGY

Before using the wheel balancer it is suggested that you become familiar with the terminology and features of the machine's components. Refer to Figures from 9 to 10 for identification and location.



Figure 9

USER INTERFACE - Figure 9

- 1. Position Indicator LEDs Displays the location for wheel weight placement.
- 2. Inside Weight Amount and Function Display Window Shows inside or left weight amount and various operation messages.
- 3. Outside Weight Amount and Function Display Window Shows outside or right weight amount and various operation messages.
- 4. Function Indicator LEDs indicating active functions and weights placement positions. They allow to set the proper workflow.
- 5. Input panel it allow the main user selections.

3.1 THE INPUT PANEL



Figure 9a

INPUT PANEL - Figure 9a

1. Diameter key with indicator

Press to select "rim diameter" mode. The diameter indicator will light up, the unit will beep. The current value will be shown on the display and can be edited.

2. Width key with indicator

Press to select "rim width" mode. The width indicator will light up, the unit will beep. The current value will be shown on the display and can be edited.

3. Offset key with indicator

Press to select "offset" mode. The offset indicator will light up, the unit will beep. The current value will be shown on the display and can be edited. Pressing the offset key in HWM enables the operator to enter the plane reference points again.

4. + key

To increase an input value (e.g. rim diameter, offset, rim width).

Hold down to change the value shown automatically.

5. Enter key

Press to confirm input (dimension, mode) or save "user" settings. The unit will beep.

6. - **key**

To decrease an input value (e.g. rim width, offset, rim diameter).

Hold down to change the value shown automatically.

7. MODE key with indicator

Press to scroll along the special modes. The MODE key indicator will light up, the unit will beep.

8. Fine key

Press to toggle the read-out accuracy between 0,25 resp. 0,05 oz. (5 and 1 grams). The unit will beep. Combined with the "MODE" key, it starts the calibration function.

9. Weight key

Press to select the required weight application mode (weight mode), the unit will beep. Combined with the "MODE" key, it starts the "user" function.

Note: If pressed for at least three seconds, it recalls directly the Normal mode (Clip-Clip) and reduces the number of ALU modes that can be selected "Quick ALU Mode".

10.Stop key

Press to stop a spinning wheel.



3.2 THE CABINET



Figure 10

CABINET - Figure 10

- 11. Display Easy to read, user friendly display featuring large LEDs and one button functions.
- Weight Storage Tray Generous storage for a variety of weight profiles and sizes as well as built in storage pockets for the standard centering cones.
- 13. Accessory Storage Four sturdy side mounted pegs are supplied for storage of additional accessories.
- Semi-Automatic Parameter Arm Rim distance and diameter is automatically input with the SAPE. The SAPE is also used in several procedures for determining accurate rim profiles and tape weight placement.
- 15. Foot Operated Shaft Lock -A foot operated shaft lock is used to stabilize the shaft during the weight placement process.
- 16. Shaft Adapter A common 40 mm size shaft is used. The easily removable shaft can be replaced for service or during use of certain wheel adapters.



Figure 10a

MAIN SHAFT LOCK

- Fig. 10a

Pedal of main shaft rotation lock, used to keep the wheel in position during weights application.

The main shaft rotation is locked when the pedal is depressed. This also facilitates tightening or loosening of the clamping nut.

Note:

This lock is designed only to facilitate orientation of the wheel and must not be used for braking the main shaft spin.



Figure 10b

SAPE PARAMETER ARM

- Fig. 10b

SAPE Arm for distance and rim diameter.

- 1 SAPE Arm, can be extended and hinged upwards.
- 2 SAPE disk to identify rrim dimensions on all types of RIM profiles.

Siepen

4.0 OPERATION OF THE BALANCER

WARNING: For operator safety please read and follow the precautions outlined on pages 1 and 2 of this manual.

NOTE: Read all instructions before proceeding with operation of the balancer.

All balancer functions are input into the main computer through the large easy to read touch panel. Although each wheel tire assembly differ in some ways all balancing jobs require basically the same procedure. The order of events to take place are:

- 1. Inspection of the wheel/tire assembly
- 2. Mounting wheel onto shaft or adapter
- 3. Selection of Balancing Mode and Preferences
- 4. Entry of wheel parameters

Note: During an Alu P SAPE Arm detection the *Easy Alu* function automatically sets the desired weight location by a suitable ALU mode selection.

- 5. Spinning the wheel
- 6. Applying the recommended weight
- 7. Check spin if desired
- 8. Dismounting the wheel

The following operation instructions will follow the basic outline above.

4.1 CHECK LIST - INSPECTION Observe Before Balancing Wheel

1. Check for proper air pressure. If not correct, inflate to correct pressure.

2. Check for any foreign material inside tire. If present, remove before balancing tire.

WATER IS FOREIGN MATERIAL!

3. Remove old weights — old weights may be improper value or in wrong location.

4. Be sure tire and wheel are free of excessive dirt, rust and large stones. Use wire brush on back side of wheel if necessary.

4.2 WHEEL MOUNTING

Nearly all standard wheels and many alloy wheels have accurately machined center holes, and they should be mounted with center cones. Accurate balancing depends on accurate mounting of the wheel and correct seating of the cone in the pilot hole. Insure that the wheel is centered on the shaft exactly as it will be mounted to the vehicle.

Before starting any balancing procedure it is very important that the wheel is mounted on the machine with the proper adaptors. An incorrect centering of the wheel will result in considerable imbalance.

There are many types of wheels and Snap-on supplies adaptors of good quality and durability for the large majority. However if you meet special wheels which may require a specific adaptor, call your Snap-on distributor.

Rims may be divided into these major groups:

- 1. Car rims with a true center hole.
- 2. Car rims without a center hole.
- 3. Car rims with an untrue center hole.
- 4. Light truck rims.
- 5. Lug centric wheels
- 6. Clad wheels
- 4.2.1 STANDARD WHEELS (back cone mount)
- Mount the wheel as detailed below in Figure 11
- 1. Mount proper cone against spring plate.



Figure 11

- 2. Mount wheel on shaft in the same manner as you would on the car.
- 3. Mount pressure cup on shaft and place against outside of wheel, follow with the Quick-nut.
- 4. Tighten Quick-nut securely with both hands. To operate the Quick-nut pull the lock-unlock lever (A, Figure 11). Slide the Quick-nut on the threaded shaft. When in contact with the rim, release the unlock lever and tighten firmly. To assist in centering the wheel properly, rotate the wheel on the shaft while tightening the quick nut.



WARNING!

FAILURE TO TIGHTEN WING NUT SECURELY MAY RESULT IN SERIOUS PERSONAL INJURY.

DO NOT USE A HAMMER TO TIGHTEN THE QUICK NUT.

TO RELEASE THE QUICK NUT, UNSCREW A FEW TURNS TO REDUCE THE AXIAL PRES-SURE, THEN PRESS THE UNLOCK LEVER AND SLIDE AWAY FROM THE SHAFT.

5. Check that the wheel rotates true by turning the wheel several revolutions while noting any excessive runout.

4.2.2 CENTERING LIGHT-TRUCK WHEELS

An optional offset spacer may be required for some light truck wheels and reverse-offset wheels that must be moved away from the balancer mounting flange. The extension adaptor is often used with the 5-1/4 inch diameter light truck cone. (p/n EEWB-5)

Install the spacer on the mounting flange, then mount the wheel, using the front cone method (Figure 12)



Figure 12

4.2.3 WHEEL MOUNTING REQUIRING SPECIAL TOOLING

Clad wheels (Figure 13): A Clad Wheel is a wheel casting that is balanced but the wheel face is not finished. To finish the wheel face a plastic chromed face is bonded to the casting.



Figure 13

A clad wheel must be centered properly from the back side of the wheel using a precision collet instead of a centering cone. A precision collet is normally a dual sided centering device with low tapers on each side and has a length of approximately 1.5 inches.

The benefit of a precision collet is it fits very precisely into the tapered machining on the back side of a cast wheel and the collet does not protrude into the wheel center. A cone also offers precision centering, but a cone can have a length from the long to short end of the taper of two inches or more. A taper cone unlike a precision collet, will intrude into the wheel center.

On many clad wheels there are plastic tabs to hold the cosmetic cover in place. It is also necessary to use a pin plate in the front of the wheel. The standard pressure cup may crack the plastic cladding.

A centering cone can break off the tabs. See section 1.6 Optional Accessories for tooling recommendations.

4.3 MODE SELECTION

The majority of balancing takes place in the default 2-plane dynamic mode which is displayed as "2 PL" (location 1). Hammer-on clip weights will be placed on both inside and outside of the rim edge. If required, select an optional weight placement mode by pressing the *Mode* button until the appropriate placement mode is displayed.

SIEDET

4.3.1 WEIGHT PLACEMENT MODES

Before Spinning the wheel (although it may be done afterwards) choose the appropriate balancing mode for the wheel. To select the various placement modes press the (9) **Weight Placement** button (Figure 14) until placement LEDs (Figure 14a) indicate desired placement positions.



Figure 14



Figure 14a

A. DYNAMIC (two planes), suggested for all steel rims. In this case the wheel weights must be clipped onto the rim edges. This function is selected as a default and the LEDs corresponding to the wheel weight location are lit on (Figure 15).



Figure 15

B. STATIC (single plane - Figure 16). Suggested for narrow rims (3" or less). Use a single corrective weight placed in the center of rim as illustrated in Figure 16.



Figure 16

- To select the STATIC Mode:
 - 1. Touch the SAPE Arm to the rim flange.
 - 2. Enter the rim width dimension.
 - 3. Press four times Alu button (9).

WEIGHT COMBINATION MODES USING THE WEIGHT SELECTION BUTTON

See (Figure 14). Pressing the weight selection button (9) will toggle the LED's to the weight default selections as shown. Balancing using a combination of hammer-on and adhesive weights as shown in Figure 17.



Figure 17

4.3.2 MOTORCYCLE MODE

When the Motorcycle Mode is active (keys 7-5, Fig.17a),



Figure 17a

only the following weight positioning options are available:

- Normal (clip clip)
- Static 1 (in the middle of the rim)
- Static 2 (on the left side of the rim)
- ALU 1 (stick stick)

Note: The *Easy Alu* function is not available when the Motorcycle Mode is selected.

To balance a motorcycle wheel:

- Install the Motorcycle adaptor EAA0260D80A.
- Install the wheel.
- Activate the Motorcycle Mode (7-5, Figure 17a).
- Apply the SAPE extension, then Acquire/Set the three wheel dimensions.
- Perform the measuring run.
- Select a Weight Mode (9 Figure 14) from the four available.

Note: At the end deselect the Motorcycle Mode to make all the weights positioning options and the *Easy Alu* function available again.







Figure 18

4.3.3 SAPE ARM POSITIONS FOR ALU WEIGHTS PLACEMENT

Fig. 18 shows the corrected reading positions of the SAPE Arm (1), depending on the required weight positions (2); adhesive weights and clip-on weights.

Weight Placement illuminated indicators indicate the weights placement positions on the rim.

- = SAPE arm application point (1).
- = / \leq = resulting in weight position (2).
- **Normal** Touch the SAPE Arm to the rim flange (**a**). Manually input the rim width dimension. This mode require the clip-on weights placement.
- Alu 1 Touch the SAPE Arm to the rim flange (a). Manually input the rim width dimension. Press once the Alu key (9). This mode uses the standardized adhesive weights placement.
- Alu 2 Touch the SAPE Arm to the rim flange (a). Manually input the rim width dimension. Press twice the Alu key (9). This mode uses the standardized adhesive weights placement.
- Alu 3 Touch the SAPE Arm to the rim flange (a). Manually input the rim width dimension. Press three times the Alu key (9). This mode uses the standardized weights placement.
- Alu 4 Touch the SAPE Arm to the rim flange (a). Manually input the rim width dimension. Press six times on the Alu key (9). This mode uses the standardized weights placement.
- Alu 5 Touch the SAPE Arm to the rim flange (a). Manually input the rim width dimension. Press seven times on the Alu key (9). This mode uses the standardized weights placement.
- Alu 1P Touch the SAPE Arm to the rim flange (b).
 Press once the *Easy Alu Toggle* key (9).
 Manually input the rim width dimension.
 The internal correction plane for adhesive weights is precisely indicated by the machine.
- **Note:** Make sure all entries are completed prior to balancing spin.
- Alu 2P Perform the SAPE Arm detection in (b-c) points. - The adhesive weights are placed where the readings are taken, according to the reading positions.
- Alu 3P Perform the SAPE Arm detection in (a-c) points. - The adhesive weight is placed where the reading is taken, according to the reading position.
- Note: The *Easy Alu Toggle* key (6), can retrieve an alternative ALU P mode.



4.4 SELECTING OPERATOR PREFERENCES

4.4.1 FINE BALANCING MODE

This balancer measures with the maximum precision available all the time, 1g / 0.05 oz, however values below 5g / 0.25 oz are shown as zero while in the normal operating mode. Values exceeding 5g / 0.25 oz are rounded to the amount of the nearest commercial wheel weight.

Press the **FINE** button to advance to the display resolution between 5g / 0.25 oz and 1g / 0.05 oz.

4.4.2 OUNCE/GRAMS CONVERSION

When the machine is first turned on it is preset to display the imbalance in ounces.

Press the **MODE** button to advance to select ounces or grams.

Select Enter to save selection.

4.4.3 RIM DIAMETER IN MILLIMETERS

The rim diameter is normally displayed in inches, however if the value in millimeters is desired. Press the MODE button until "PAX/mm" is NOT illuminated to display in inches, when lit the unit displays in mm.

4.5 ENTER RIM PARAMETERS

4.5.1 Rim Distance (offset) - Move the rim offset arm to the edge of the rim, touch the pointer to the rim edge as illustrated in Figure 19 and hold steady for about a second. The beeper will sound when the distance and diameter values are calculated and entered. Return the arm to its fully in and down position on the balancer. Do not allow the measurement arm to "dangle" down in front of the balancer.



Figure 20

4.5.2. Measure/Enter rim width using rim width caliper. Measure wheel where corrective clip-on weight would be applied, Figure 20.



Figure 19



Figure 21

Press the Width entry key, Figure 21-W, and enter the measured width by pressing +/- keys until the desired value appears in the display. Select Enter to save selection.



4.5.3 Manual Parameter Entry

In the event of automatic SAPE failure, the parameter values can be input manually. See manual entry of rim width in the previous paragraph.



Figure 22



Figure 23

4.5.3.0 Manual Rim Diameter Entry - Select the Manual Diameter button. Read the rim diameter marked on the sidewall of the tire (Figure 22 and 23). Press the Diameter Button (D) and enter the measured rim diameter by selecting the +/- keys until the desired value appears in the display.

Select Enter to save selection.



Figure 24

4.5.3.1 Manual Distance Entry - Move the distance SAPE Arm to touch the inner edge of the wheel where weights are to be placed and observe the reading on the scale of the distance SAPE. See Figure 24. Press manual Wheel **Offset** button (O) followed by selecting the +/- keys until value is displayed in the display window. Select Enter to save selection.

NOTE: The parameter arm must be in the Home rest position when the balancer is powered up.

4.6 Easy Alu FUNCTION

The *Easy Alu* function automatically recognizes the desired weight location by placing the SAPE Arm in the correct locations.

Note:

Alu 4 and Alu 5 are not included in the *Easy Alu* function. They require manual setting by the operator.

4.6.1 Automatic rim dimension reading and Alu P Mode selection

Preparations:

- Compensation run carried out, if necessary.
- Wheel correctly clamped.

Important: The OK indication and recommendation for optimization, as well as the optimization procedure itself, will only be accurate if the rim width is correctly entered (Manual Input).

Automatic rim distance and diameter reading with an internal SAPE Arm

 Move the SAPE Arm into position on the rim to select the initial weight application position (internal rim side). Keep it in this position until an audible signal is heard.



Figure 25

Only for Alu2P and Alu3P (Fig. 25):

• Position and hold the internal SAPE in the second position on the rim to select the application position on the right side of the rim.

Shortly afterwards the machine emits an audible signal to indicate that the machine automatically saves the weight application coordinates.

• Move the SAPE Arm to the idle position.

At this point you can change the Alu mode suggested by the machine, using the "*Easy Alu Toggle*" function.

Do this by pressing the button

• Spin the assembly.



4.7 SPINNING THE WHEEL

1) Manually activate the lever (**1**, Fig.26) to spin the wheel. Wheels must turn clockwise.

2) The operator must release the lever (1) once the rotation speed is reached.

The measurement is completed as soon as the direction indicators light up.

The unit beeps.

The brake will be applied automatically.



Figure 26



Figure 27



The following weight types and application methods are available:

- Clip-on weights: Always apply by hand
- Stick-on weights: Can be applied by hand or using the SAPE head for the Alu 2P, Alu 3P or easy weight mode.

Hand applied weights **MUST** be applied exactly perpendicular to the shaft (12 o'clock position). After Spinning the wheel look at the rotation indicators for the left plane of the wheel, Figure 27-**A**. As the correct Wheel Angle Position (WAP) gets closer more indicators light up. When all the indicators are ON, the WAP indicator will also light up, Figure 27-**B**. Follow same procedure for placing weight in the right plane.

Note: When the correct angle is reached, all the rotation indicators should be ON. If the wheel has been pushed too far, only the indicators of the other half will come ON. If this happens, the wheel must be slowly turned in the opposite direction until the WAP position is reached. The weight amount to be applied in that plane is shown on the display.

Attaching a clip-on weight.

Refer to Figure 28. Clip-on weights must always be applied in the 12 o'clock position. The lip should rest on the rim edge. Use the weight pliers to position it. In STATIC mode only the left hand display is used.

Attaching a stick-on weight.

ALU or STATIC weight modes only: Refer to Figure 28a. Apply the weight on the rim in the 12 o'clock position, always by hand.

Note: With STATIC weight modes, always apply the weight at the rim center line. If not possible, split the weights evenly and apply on another surface of the rim (symmetrical to the rim center line).



Figure 28



Figure 28a

EDER

5.1 Alu P WEIGHTS APPLICATION WITH THE SAPE ARM

When Alu 2P or Alu 3P is selected (See Figure 27a-**C**), The SAPE Arm is used to determine the desired weight location, Extend the SAPE to the inner position and wait a few seconds for the placement to register, the placement LED will flash during this time. See figure 27a-**D**.



Extend the SAPE Arm to the outer position and wait for the signal to return the arm to home. Spin the assembly.

Use the SAPE Arm to position the corrective weights as indicated by the display. Rotate the wheel until all position LEDs are lit (**A**+**B**, Figure 27a). If correcting the left plane, the right amount window will display a series of dashes while searching for the placement location.

While moving the arm, a beep indicates when the correct application position has been reached. The weight amount will then be displayed and flash and the WAP indicator will lite up (Figure 27a-**B**). Press the foot pedal to hold the wheel in this position. Apply the weight to the correct point on the rim.



Figure 28b

NOTE: Clean the area where the weight will be placed before attaching the adhesive weights. In compliance with the imbalance detected, approach at the SAPE head the suitable adhesive weight.(1, Figure 28b). Remove the protective tape (2, Figure 28b) from the stick-on weight and apply it to the correct point on the rim.

Split Weight Mode or sometimes called *Spoke Mode* can be invoked if desired. See chapter 6.0.

NOTE: Either left or right plane can be corrected first.

Rotate the wheel to the next position, put the stick-on weight on the SAPE Arm and apply the weight for the remaining position. After applying the balance weights perform a Check Spin.

It is good practice to perform a check spin after applying the weights. Spin the wheel. Having finished the Run, if the wheel is balanced correctly, both the numerical indicators should indicate 000. To check how much imbalance is left: Select the FINE key. The operator should decide if applying additional weight is required.

Results recalculation. After Spinning a wheel it is possible to enter new rim data or select another weight mode. The results are recalculated automatically. Selecting another weight mode such as between NORMAL, ALU and STATIC no additional steps required either.

SIEDER





Figure 29b



6.0 SPOKE BALANCING MODE

When spoke wheels are balanced, the behind-thespokes placement mode (also called split weight mode) allows balance weights which would have to be fitted between two spokes according to the measured unbalance (hence would be visible from outside) to be placed in hidden position behind two spokes adjacent to the unbalance location. After a measuring run the electronic unit calculates the behind-the-spokes placement automatically and reads the relative balance weight locations on the screen. The operating steps for the behind-the-spokes placement mode are described and illustrated below figure 29b

6.1 SPLIT WEIGHT MODE (SWM)

- 1. Select desired placement mode, ALU-2 or 3 will both function with spoke mode. Must be behind the wheel weight position to select.
- 2. Measure position one and two with the SAPE Arm.
- 3. Perform a balance run.
- 4. Place inner corrective weights. Hold wheel assembly secure with the foot brake when placing weights.

HINT: Press the "Plus" key to quick spin the tire to the next weight correction position.

- 5. Once you have a weight amount displayed. Rotate the outer plane to the weight position indicated when all LEDs are illuminated.
- 6. Press the Mode key. Then press Enter.
- 7. The Spoke icon should illuminate as well as the Mode LED.
- 8. Rotate the wheel to the first spoke or closest spoke position with P1 on the display. Press press the enter key for position one. Figure 29c
- Rotate the wheel to the second or next closest spoke position with P2 on the display and press enter. Figure 29d
- 10. The weight amount for correction is now divided by two and displayed between the two spokes select.
- 11. Place the outer corrective weighs using the SAPE Arm





Figure 30a



Figure 30b

Figure 30c



Figure 30f



Figure 30g



7.0 USER CALIBRATION

The EEWB330B Balancer features a User Calibration which requires only a few minutes to complete. The operator can electronically calibrate the rotating masses on the machine; which is called User Calibration. Perform this procedure when the balancer has been moved, disturbed, or whenever accuracy is questioned. If the calibration process fails a service technician must be called to perform a complete calibration.

A calibration run requires little more time than a regular balance run.

Procedure;

- Balance a wheel (15" x 6,5"), as a NORMAL weight mode, to less than 5 grams per plane.
- Press the "MODE" key and the "FINE" key together for 5-7 seconds. See Figure 30a.
 The initial display reads "C 14", See Figure 30b.

- Press "**ENTER**" once to initiate procedure. The display shows "**CAL 1**". See Figure 30c.
- Remove any cones or adapters from the shaft. See Figure 30d.

Note: Continue the spin until the unit beeps. When compete, the display shows "**CAL 2**". See Figure 30e.

- Mount the User Calibration Weight, refer to Figure 30f. Spin the shaft.
- After a few seconds the display equals **C** ---, Figure 30g. The User Calibration was performed correctly.

Any (operator) error causes the program to exit. Unscrew the Calibration weight from the flange and put it back in its designated place for safe keeping.





Figure 31a

8.0 USER FUNCTIONS

8.1 Data Recall

Use this function to store or recall rim data (wheel type, diameter, width, Offset, fine mode, oz. mode and mm mode) in or from the memory. 4 sets of wheel data (the so-called user data) can be stored.

When it is turned ON the balancer sets the wheel data regarding user A to the system default values and sets the current user to user A.

To activate:

- Press the "MODE" and the "Weight Placement" keys simultaneously for 3 seconds. See Figure 31a.
- The function starts with the SAVE option.
- The data can be saved to the user displayed on the right.

To clear the data (without saving):

• Select Enter when user "- -" is displayed.

To save data:

- Select + or to scroll along User A, b, C or d.
- Select Enter to save to the selected user.

The function proceeds with the RECALL option. The data can be recalled from memory by selecting the appropriate user. The selected user will be the new current user, such as User b.

No recall required (no change in user required):

• Select Enter when user "- -" is displayed.

To recall data:

- Select + or to scroll along User A, b, C or d.
- Select Enter to recall the selected user.
- The current available wheel data will be replaced by the recalled data such as: "b".





Figure 31b



Figure 31c

8.2 WEIGHT UNIT TOGGLE MODE

Setting the basic weight unit: oz/grams

Select this mode to change the unit of measure of the weight before or after carrying out a balancing operation.

- Press the "MODE" key until the weight units indicator flashes. The "oz" indicator will start flashing.
- The display will now look like Figure 31b.
- Press Return.

The weight setting status now calculates weights using a different unit of measure (from grams to ounces or from ounces to grams).

The program returns to the main menu.

8.3 DIMENSION UNIT TOGGLE MODE

Setting the basic unit of measure for diameter and width: inches/mm

Select this mode to change the unit of measure of the diameter and width before or after carrying out a balancing operation.

- Press the "MODE" key until the dimensional units indicator blinks.
- The "mm" indicator will start flashing.

The display should now appear as shown in Figure 31c.

Note: The operator can now select the units in steps of 1 mm if the mm mode has been selected.

Select return.

The state of the diameter and width dimension units will toggle (inch to mm, or mm to inch).

Note: The unit is set to default to inches.

Offset is always measured and shown in millimeters.

The program returns to the main menu.

SIEDER





9.0 OPTIMIZATION/WEIGHT MINIMIZATION. Balancing optimization program cycle

The following is a description of the balancing optimization program cycle (code OP) and weight minimization (code UN).

Balancing optimization

Figure 5-32

If after the measuring run the imbalance in the left or right correction plane and/or the static imbalance is more than 30 grams, perform automatic optimization by activating the **FINE+ENTER** key (**3+1**).

• Before optimization check that the rim dimensions have been set correctly.

You cannot correct the data later.

- Demount the tire and clamp only the rim for the compensation run.
- Press the ENTER key (1).

The OP.1 reading appears (Fig. 5-33).

- In all figures in which the valve symbol appears on the edge of the rim, shift the tire on the rim then press the **ENTER** key (1) to set the valve position (exactly perpendicular to and above the main shaft).
- Readjust the rim so that the valve is exactly perpendicular to and above the main shaft.
- Press the **ENTER** key (1) to acquire the valve position.

The OP.2 reading appears.

An incorrect valve position entry can be corrected afterwards.

Weight minimization

If no optimization, but only weight minimization (i.e. without compensation run for the rim without tire), proceed as follows:

- Clamp the complete wheel (rim and tire).
- Press FINE (3) + ENTER key (1) if minimization is started separately from optimization.

The **OP.1** reading appears.

• Press the **FINE** key (**3**) to activate the weight minimization program.

The **Un.3** reading appears;

Run the minimization program.

• With program **OP.2** the rim compensation run can still be omitted. Go to the next step in the program by pressing the **FINE** key (3).

The UN.4 reading appears.

• Continue the minimization program.

The valve position entered with **OP.1** is automatically used.





Continuing balancing optimization

(Fig. 5-34)

• START the rim compensation run, without the tire. After the measuring run the **OP.3** reading appears.

• Mount the tire and inflate correctly (see note below).

Note

For mounting and demounting (tire changer) and tire turning or readjustment on the rim, always apply a sufficient amount of tire lubricant on the tire beads and the rim edges and shoulders. Each time the position of the tire is changed on the rim, inflate the tire to overpressure (approx. 3.5 bar) then deflate to correct tire pressure.

Make sure the centering line is correctly positioned on the tire bead.

- Clamp the wheel.
- Position the valve exactly perpendicular to and above the main shaft.
- Press the ENTER key (1) to acquire the valve position.

OP.4 appears (Fig. 5-34).

• Spin the wheel (START).

The measuring run is carried out. After the measuring run two readings are possible:

OP.5 - H1

Further optimization is not recommended, but possible.

OP.5 – *I* (1 Reference mark **Fig. 5-35**) Continue with the OP program.

Reading OP.5 - H1

If **OP.5** - **H1** appears, further optimization is not recommended, since the measurement values which activated the optimization recommendation are below the limit value. However, it is possible to continue optimization for the most silent possible wheel running, reducing imbalances below the limit value (critical vehicle).

To continue optimization

 To continue with the OP program proceed as specified for OP.5 – I (given below).

To abort optimization

 Press the STOP key to return to the balancing program and balance the wheel according to the readings (@ 5.9).

5-37



5-32



5-34



Reading OP.5 - I (1 Reference mark Fig. 5-35)

- After the measuring run readjust the wheel following the direction indicator and make a chalk mark on the right side of the tire exactly perpendicular to and above the main shaft.
- Readjust the tire on the rim so that the reference mark made is aligned with the valve (use tire changer).
- Clamp the wheel on the balancer and readjust it until the valve is exactly perpendicular to and above the main shaft.
- Press the **ENTER** key (1) to acquire the valve position.

The OP.6 reading appears (Fig. 5-34).

• Spin the wheel (START).

After the measuring run four readings are possible:

II - OP.7

Proceed with the OP program. It is recommended that the tire be turned over on the rim.

OP.7 - II

Proceed with the OP program. It is recommended to shift the tire on the rim (manual rotation).

H0

Optimum condition has been achieved and cannot be improved.

H2

Silent running cannot be improved.

• Press STOP (5) to exit.

However, it is possible to readjust the tire relative to the rim to achieve significant weight minimization (i.e.: smaller balance weights) without having an adverse effect on silent running.

Depending on the readings, there are several possibilities for proceeding with the program. These possibilities are described below.

Reading II - OP.7 (Fig. 5-37)

Turn the tire over on the rim (the left display bars are rotating).

Option 1: Turn the tire over on the rim (normal program).

- Readjust the wheel according to the left direction indicator and make a double mark on the left side of the tire exactly perpendicular to and above the main shaft.
- Remove the wheel from the machine.
- Turn the tire over on the rim and readjust until the double mark coincides with the valve.
- Clamp the wheel on the balancer and readjust it so that the valve is exactly perpendicular to and above the main shaft.
- Press the **ENTER** key (1) to acquire the valve position.







5-34



5-37





• Spin the wheel (START).

If balancing optimization (silent running) has been carried out correctly (according to the program cycle), after the check run the machine automatically returns to the type of weight positioning previously selected and indicates the residual dynamic imbalance on the wheel. • Balance the wheel according to the readings.

Both optimization and balancing are accomplished.

Message **E9**

Message E9 means that at least one error occurred during the optimization cycle. Press the **STOP** key (5) to exit the optimization program and repeat optimization if necessary.

Option 2: Do not turn the tire over on the rim

• Press the **FINE** key (3).

The result is recalculated.

Reading OP.7 - II or H0 or H2 appears

 To go to *II - OP.7* (turning over the tire) press the FINE key (3) again.

Option 3: Abort optimization

• Press the **STOP** key (5) to exit the OP program and return to the balancing program.

The imbalance on the wheel is shown on the readout.

• Balance the wheel according to the readings.

Reading OP.7 - II (Fig. 5-37)

Readjust the tire on the rim (the right display bars light up permanently).

Option 1: Readjust the tire on the rim (normal program)

- Readjust the wheel following the right direction indicator and make a double mark on the right side of the tire exactly perpendicular to and above the main shaft (**Fig. 5-38**).
- Remove the wheel from the machine
- Readjust the tire on the rim until the double mark coincides with the valve (Fig. 5-39).
- Clamp the wheel on the balancer and readjust so that the valve is exactly perpendicular to and above the main shaft.
- Press the ENTER key (1) to acquire the valve position.

Reading OP.8 appears (Fig. 5-34).

• Spin the wheel (START) (check run).

SIEDET



5-32



5-35



If balancing optimization (silent running) has been carried out correctly according to the program cycle, after the check run the machine automatically returns to the type of weight positioning previously selected and indicates the residual dynamic imbalance on the wheel.

• Balance the wheel according to the readings. Both optimization and balancing are accomplished. Message *E9*

Message E9 means that at least one error occurred during the optimization cycle. Press the **STOP** key (5) to exit the optimization program and repeat optimization if necessary.

Option 2: do not adjust the tire on the rim

• Press the **STOP** key (**5**) to exit the OP program and return to the balancing program.

The imbalance on the wheel is shown on the readout.

• Balance the wheel according to the readings.

Reading HO

- Press the **STOP** key (**5**) to exit the OP program and return to the balancing program.
- The imbalance on the wheel is shown on the readout.
- Balance the wheel according to the readings.

The optimum balancing optimization condition has been achieved and cannot be improved.

Reading H2

Silent wheel running cannot be improved. However, it is possible to achieve weight minimization (readings with code *UN*.).

Option 1: Weight minimization

• Press the **FINE** key (**3**) to continue the program. As a result reading is *II* - *Un.7* or *Un.7* - *II*

Option 2: Abort optimization

- Press the **STOP** key (**5**) to exit the OP program and return to the balancing program.
- The imbalance on the wheel is shown on the readout.
- Balance the wheel according to the readings.





Weight minimization program cycle

If the rim compensation run was omitted and the **FINE** key (**3**) was pressed to go directly into the minimization program (reading **Un**.), proceed as follows.

- Clamp the wheel.
- Position the valve exactly perpendicular to and above the main shaft.
- Press the ENTER key (1) to acquire the valve position.

Reading Un.4 appears (Fig. 5-34).

• Spin the wheel (START).

The measuring run is carried out. After the measuring run two readings are possible:

Un.5 - H1

Further minimization is not recommended, but is possible.

Un.5 – I (1 Reference mark **Fig. 5-35**) Continue with the UN program.

Reading Un.5 - H1

If **Un.5** - **H1** appears, further minimization is not recommended since the measurement values do not exceed the limit values. However, it is possible to continue minimization so as to achieve an improvement, if only slight (e.g.: for critical vehicles).

To continue minimization:

- Proceed as indicated for reading Un.5 I.
- To abort minimization:
- Press the **STOP** key (5) to return to the balancing program and balance the wheel according to the readings.

Reading Un.5 – I (1 Reference mark Fig. 5-35)

- After the measuring run readjust the wheel according to the direction indicator and make a chalk mark (Fig. 5-36) on the right side of the tire exactly perpendicular to and above the main shaft.
- Readjust the tire on the rim so that the mark coincides with the valve (use the tire changer Fig. 5-37).
- Clamp the wheel on the balancer and readjust it so that the valve is exactly perpendicular to and above the main shaft.
- Press the **ENTER** key (1) to acquire the valve position.

Reading Un.6 appears (Fig. 5-34).

Spin the wheel (START). The machine performs the second measuring run with the tire. After the measuring run three readings are possible:

II - Un.7

Proceed with the UN program. It is recommended that the tire be turned over on the rim.

5-37

STEPET











Un.7 - II Proceed

Proceed with the UN program. It is recommended that the tire be readjusted on the rim.

H0

The optimum minimization condition has been achieved and cannot be improved.

Depending on the readings, there are several possibilities for proceeding with the program. These possibilities are described below.

Reading II - Un.7

Turn the tire over on the rim (the left display bars are rotating).

Option 1: Turn the tire over on the rim (normal program)

- Readjust the wheel according to the left direction indicator and make a double mark on the left side of the tire exactly perpendicular to and above the main shaft (Fig. 5-36).
- Remove the wheel from the machine.
- Turn the tire over on the rim and readjust until the double mark coincides with the valve (Fig. 5-37).
- Clamp the wheel on the balancer and readjust it so that the valve is exactly perpendicular to and above the main shaft.
- Press the **ENTER** key (1) to acquire the valve position.

Reading Un.8 appears (Fig. 5-34).

• Spin the wheel (START) (check run).

If weight minimization was carried out correctly (according to the program cycle), after the check run the machine automatically returns to the type of weight positioning previously selected and indicates the residual dynamic imbalance on the wheel.

• Balance the wheel according to the readings.

Both weight minimization and balancing are accomplished.

Message E9

Message E9 means that at least one error occurred during the minimization cycle. Press the **STOP** key (5) to exit the minimization program and repeat minimization if necessary.

Option 2: Do not turn the tire over on the rim

• Press the **FINE** key (**3**). The result is recalculated. Reading **Un.7 - II** or **H0** appears

Option 3:

- Press the **STOP** key (5) to exit the minimization program and return to the balancing program
- The imbalance on the wheel is shown on the readout.
- Balance the wheel according to the readings.



1 2 MODE 5 3 FINE STOP 4

5-32

Reading Un.7 - II (Fig. 5-37)

Readjust tire on the rim (the right display bars light up permanently).

Option 1: Readjust the tire on the rim (normal program)

- Readjust the wheel according to the right direction indicator and make a double mark on the right side of the tire exactly perpendicular to and above the main shaft (**Fig. 5-38**).
- Remove the wheel from the machine.
- Readjust the tire on the rim until the double mark coincides with the valve (**Fig. 5-39**).
- Clamp the wheel on the balancer and readjust it so that the valve is exactly perpendicular to and above the main shaft.
- Press the ENTER key (1) to acquire the valve position.

Reading Un.8 appears (Fig. 5-34).

• Spin the wheel (START) (check run).

If weight minimization was carried out correctly (according to the program cycle), the machine automatically returns to the type of weight positioning previously selected and indicates the residual dynamic imbalance on the wheel.

• Balance the wheel according to the readings.

Both weight minimization and balancing are accomplished.

Message **E9**

Message E9 means that at least one error occurred during the minimization cycle. Press the **STOP** key (5) to exit the minimization program and repeat minimization if necessary.

Option 2: Do not readjust the tire on the rim

• Press the **STOP** key (**5**) to exit the minimization program and return to the balancing program

The imbalance on the wheel is shown on the readout.

• Balance the wheel according to the readings.

Reading HO

The optimum minimization condition has been achieved and cannot be improved.

• Press the **STOP** key (5) to return to the balancing program and continue according to the readings.

SIEDET

10.0 TROUBLE SHOOTING

If a problem arises with the wheel balancer, proceed in the following order to solve the problem:

- Rethink the last steps taken. Did you work according to the manual? Did the unit work as described and expected?
- 2. Check the unit according to the points listed in this chapter.
- 3. Call Technical Support at 800-225-5786.

When switched on, nothing lights up.

- 1. Power switch in OFF position.
- Set power switch in ON position.
- 2. No power cable connected.
- Connect power cable to power outlet.
- 3. No mains power
- Check power supply, power system fuses
- 4. Unit fuse(s) blown.
- Replace unit fuse(s).
- If the fuse(s) has (have) recently been replaced,Call Technical Support at 800-225-5786. to check
- the unit.

When switched on, a beep is heard for 1 second.

- 1. Configuration error.
- Call Technical Support at 800-225-5786.

Display appears to freeze or lock up.

- 1. The unit may be in a program, waiting for a specific action.
- Finish the program currently in use.
- Switch off the unit.
 Wait for 20 seconds, switch on the unit.
 Proceed.
- 2. Power to the balancer may have been interrupted.
- Switch off the unit.
 Wait for 20 seconds, switch on the unit.
 Proceed.
- If this happens frequently, have your power system checked. If that is okay, call technical service team.

SAPE Arm inputs differ from wheel dimensions stated on rim or tire.

- 1. Did you position the SAPE Arm correctly?
- Refer to Chapter 5.6.1.
- 2. Check the offset input of the SAPE Arm by entering manually.
- Refer to the scale on the SAPE Arm.
- If not identical, proceed with step 4.

- 3. Check the diameter of the spot on the rim where the diameter has been measured.
- If not identical, proceed with step 4.
- 4. Calibration is required.
- Have the SAPE Arm calibrated.

Balancing results are unreliable.

- 1. The balancer may not be installed properly.
- Make sure the unit rests on its 3 feet only.
- Make sure the floor is not relaying shocks or vibrations, for example from compressors or trucks passing close to the unit.
- 2. The wheel may be mounted incorrectly.
- Check the hub, cones and adapters for play.
- Use appropriate spacers to eliminate play.
- Perform measuring unit calibration.
- 3. The electronics are faulty.
- Call Technical Support at 800-225-5786..

A mode or indicator is continuously shown on the screen.

- 1. A power fluctuation may have occurred.
- Switch off the unit. Wait for 20 seconds, switch on the unit.
- Call Technical Support at 800-225-5786.



10.1 SYSTEM MESSAGES

The wheel balancer can show messages to the operator. These may be error related (E-codes) or warnings (H-codes). The codes will be described in the following chapters.

Whenever a code appears:

- Make a note of it;
- Look up the code in the list. If the code is not described, call service team;
- Perform the steps described.

In special cases, or if the need arises, some operating modes or states can be changed by entering the appropriate codes (C Codes).



Figure 9a

10.1.1 C CODES Selecting and changing a code.

Example for code C0 (Fig. 9a)

 Press and hold down together the "MODE" (7) and "FINE" (8) keys for 7 seconds.

The C codes selection condition appears.

- Press one of the "+" (4) or "-" (6) keys until the readout shows the desired code number (e.g.: C 0).
- Press the **ENTER** key (5) to acquire the selection.

The right number readout shows the current state, e. g.: "0" which in this case means switched off.

If the desired state is already on the readout:

• Press the **STOP** key (**10**, **Fig. 9a**) once to return to C codes selection, and a second time to definitively exit and return to the operating mode.

If the desired state is not that shown by the readout, but needs selecting, proceed as follows:

 Press one of the "+" or "-" keys until the right readout shows the desired condition (e.g.: "0"). Now two options are possible:

Option 1

- Press the ENTER key to acquire the selection.
- Press the STOP key to return to the operating mode.

The operating mode change is complete and is saved until a new setting is entered. When the machine is switched off the settings are not deleted, and at each subsequent start up they appear as previously set up until changed again.

Option 2

Cancel selection of code C just set and return directly to the operating mode:

Press the STOP key twice consecutively.

Note: Code C4, Compensation of the clamping means, cannot be transferred to the permanent memory.

Below are the change codes available and the relative selections possible.

Code C0

Setting operating modes preset by the factory:

- Select Code C0
- Select one of the following options:
- 0* = No action
- 1 = Set the default values (state 1 appears briefly)

Note: The selection is permanently acquired.

Code C3

Selecting unbalance readings in grammes or ounces

0 = Readings in grammes

1* = Readings in ounces

This mode can be transferred to the permanen memory.

Code C4

Compensation of residual unbalance, if any, in the clamping means.

High precision measurement.

Every time the clamping means are substituted, compensation must be deleted or carried out again with the new means fitted.

Resetting the operating state to 0 cancels the clamping means compensation.

The compensation is also cancelled following:

- Balancer calibration or recalibration,
- Unbalance optimization,
- Balancer switch off.

JIEDEN

- Select Code C4
- Select one of the following options:

0 =	Carry out	compensation
-----	-----------	--------------

1 = Compensation completed

0 = Switch off compensation again after the measuring run.

Note: The present operating mode cannot be transferred to the permanent memory.

Code C8

Selecting the limit (threshold) value for suppression of minor unbalance readings in grams, or ounces. The unit of measurement (g or oz) depends on the setting (Refer to 8.1).

Ounces:

Range 0.12 to 0.71 oz

Factory-adjusted to 0.18* oz

Select another limit, e. g.: 0.50 oz

- Select Code C8
- Set the value 0.50

Press ENTER

Note: The selection is permanently acquired.

Grams:

Range 3.50 to 20.0 g Factory-adjusted to 5.0* g Select another limit, e. g.: 5.50 g

- Select Code C8
- Set the value 5.50
- Press ENTER

Code C11

Main shaft stop position.

The positioning brake stops the main shaft close to the correction position by initiating pulsing braking. The positioning brake is activated after switch on and after a measuring run has been carried out and found an unbalance greater than the limit value.

- Select Code C11
- Select one of the following options:

0 = No positioning brake after measuring run.

- 1*= Positioning brake after measuring run for left plane.
- 2 = Position brake after measuring run for right plane.

Note: The selection is permanently acquired.

Code C12

Measuring spin counter.

Example: 222,123 measuring runs completed:

- Select Code C12
- Select one of the following options:
- 1 =Total number of measuring runs completed
- 2 =Total number of measuring runs where balancing was successfully completed, indicated by OK
- 3 =Total number of optimizations or minimizations
- 4 =Total number of measuring runs in Service mode
- 5 =Total number measuring runs since last calibration

Every measuring run completed is saved. Maximum count is 999,999 measuring runs. Once this number is reached, the counter is reset to zero. The information is primarily useful for statistical purposes, for example, to monitor the endurance of faulty parts, or monthly (yearly) use of the machine, etc. The measuring runs performed while the machine is switched on are transferred to the permanent memory and added when it is switched off.

Note: The total counter (option 1) cannot be deleted.

Code C14 Readjustment of the machine by the operator

• See instruction on chapter 7.0 of this manual.

Code C21

This code provides information about the program version and the balancer model name

- Go into code C21.

Information about the software version appears.

- Press the "-" key to view the Kernel version. The information is visible for as long as the key is pressed.

- Press the "+" key or the "FINE" key to view the balancer model.

Note: The information is visible for as long as the key is pressed.



Code C28

Displays the error codes saved by the balancer (a maximum of 10) and clears the error memory.

The last 10 different error codes are saved in the error memory so that they can be called up and consulted by the wheel balancer operator for remote diagnosis of malfunctions.

The most recent error code is saved in memory location 1. Previous error codes are gradually shifted down the memory list.

Go into code C28.

REVIEWING THE ERROR COUNTERS

- Press and release the "+" or "-" key to scroll through the list of errors.
 - Note: When the key is pressed the number of the error in the list is shown, whilst when the key is released the corresponding code appears.
- Press the **MODE** key to make the error number appear again (on the left) and the total number of times that error was repeated since the last time the memory was cleared (on the right).

ZEROING THE ERROR COUNTERS

- Press ENTER.
- Make the selection.
 0* = Do not clear the error memory
 1 = Clear the error memory
- Press ENTER.

10.1.2 E-CODES

When the E-code is displayed, a low beep is generated. Whenever a code appears:

- Write it down
- Look up the code in the list. If the code is not described, call service.
- Perform the steps described.

The setup of this chapter is: Code Description

- Step(s) to be performed.
- Some error messages are displayed for approx. 3 seconds on the display of the right side.
- To clear the error code immediately press the STOP key.

E9

Optimization / minimization was not carried out correctly. 1. Wheel was not exactly centred on clamping means for at least one run.

2. Tire was not centred on rim for at least one run.

3. Valve position was not set and acquired correctly at least once.

4. Wrong reference mark (single or double) was used when readjusting the tire.

5. Wheel moved on clamping means during a measuring run (-7.1.3)

E10

SAPE Arm removed from idle position during wheel spin.

• Bring SAPE Arm to the idle position (fully in and down).

- Re-spin the wheel without touching the SAPE Arm.
- If the error appears again, have the SAPE Arm calibrated (by the service department).

Display clears after several seconds.

E11

During start-up the SAPE arm is not in the idle position.

• Move the SAPE Arm back carefully to the idle position. The error should disappear within a few seconds.

 If the error appears again, contact the service department.

Note: By pressing **STOP** you can continue to use the machine but all the wheel data must be inserted manually (@~ 4.5.3).

SIEDEN

E22

Speed low

The rotation speed of the wheel has not reached the minimum limit needed to enable balancing.

• Check that the brake (pedal) or wheel is not accidentally blocked.

- Check that something is not braking or obstructing the wheel.
- Check the power supply.
- Fit the wheel correctly.
- Contact Technical Support at 800-225-5786.

E24

Velocity fluctuations

If the speed of the wheel to keep to the need to compensate.

- Check that the wheel is not obstructed or impeded by something.
- · Check the power supply.
- Fit the wheel properly.
- Call Technical Support at 800-225-5786.

E25

Reverse error.

The shaft is rotating at a certain speed but in the wrong direction.

- Apply the brake.
- Contact Technical Support at 800-225-5786. The display clears when rotation stops.

E26

No acceleration.

No shaft acceleration has been registered.

Contact Technical Support at 800-225-5786

E27

Slipping registered.

The wheel slips on the shaft.

• Fit the wheel correctly.

E28

Speed limit reached.

Contact Technical Support at 800-225-5786.

E50

Manufacturer's calibration incomplete

Contact Technical Support at 800-225-5786.

E51

Calibration failed

- Switch unit off, wait for 20 seconds.
- Switch unit on.
- Retry calibration, or:
- Contact Technical Support at 800-225-5786

E52

The calibration weight is on the opposite side to the calibration carried out by the manufacturer.

• Fit the User Calibration Weight correctly on the left side of the flange. Repeat Calibration.

Contact Technical Support at 800-225-5786

E82

Fault during self-test at start-up.

- Switch unit off, wait for 20 seconds.
 - Switch unit on.

E92

During the second attempt the SAPE Arm for distance and rim diameter was still not in the home position. Both SAPE Arms are rendered inoperative.

• Wait 5 seconds, or press the STOP key to continue.



10.1.3 H CODES - WARNING H0

Wheel silent running cannot be improved with balancing optimization.

H1

Further optimization is not recommended but is possible.

H2

Weight minimisation is recommended, further optimization does not bring improvements.

H80

Recalibration was not set up. As a result, it cannot be performed by the operator.

Press the STOP key to clear the message. Call the service team for machine calibration.

H82

The self-test was disturbed (e.g.: by turning the wheel). The message is displayed for 3 seconds, then the measurement is repeated (max. 10 times) or aborted by pressing the STOP key.

H90

Wheel acceleration was too slow, or braking was too weak after a measuring run.

If the main shaft does not reach the required speed, check that the brake is not activated or the weight of the wheel is too great. In this case:

Release the brake.

Make sure that the shaft with the wheel clamped on it can rotate freely.

Turn the wheel by hand, then run the START.

If the error cannot be eliminated, call the service team.

H91

Speed variations during measuring run. The brake may be ON. Release the brake.

Make sure that the shaft with the wheel clamped on it can rotate freely.

Repeat the run.

11.0 MAINTENANCE



BEFORE ANY MAINTENANCE OR REPAIRS ARE ATTEMPTED THE MACHINE MUST BE DISCONNECTED FROM THE ELECTRIC SUPPLY.

This balancer does not require any special maintenance but the following precautions are required:

Periodically was all plastic parts with a glass cleaner, wipe with a dry cloth.

Clean all adapters regularly with a non flammable liquid detergent. Lubricate with a thin layer of oil.

Periodically perform a routine calibration as outlined on chapter 7.0 of this manual.

WARRANTY/SERVICE AND REPAIR

Snap-on® Tools Limited Two (2) Year Warranty

Snap-on Tools Company (the "Seller") warrants only to original purchasers who use the Equipment in their business that under normal use, care and service, the Equipment (except as otherwise provided herein) shall be free from defects in material and workmanship for two years from the date of original invoice. Seller does not provide any warranty for accessories used with the Equipment that are not manufactured by Seller.

SELLER'S OBLIGATIONS UNDER THIS WARRANTY ARE LIMITED SOLELY TO THE REPAIR OR, AT SELLER'S OPTION, REPLACEMENT OF EQUIPMENT OR PARTS WHICH TO SELLER'S SATISFACTION ARE DETERMINED TO BE DEFECTIVE AND WHICH ARE NECESSARY, IN SELLER'S JUDGMENT, TO RETURN THIS EQUIPMENT TO GOOD OPERATING CONDITION. NO OTHER WARRANTIES, EXPRESS OR IMPLIED OR STATUTORY, IN-CLUDING WITHOUT LIMITATION ANY IMPLIED WARRANTY OF MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE, SHALL APPLY AND ALL SUCH WARRANTIES ARE HEREBY EXPRESSLY DISCLAIMED.

SELLER SHALL NOT BE LIABLE FOR ANY INCIDENTAL, SPECIAL OR CONSEQUENTIAL COSTS OR DAM-AGES INCURRED BY PURCHASERS OR OTHERS (including, without limitations, lost profits, revenues, and anticipated sales, business opportunities or goodwill, or interruption of business and any other injury or damage).

This warranty does not cover (and separate charges for parts, labor and related expenses shall apply to) any damage to, malfunctioning, in-operability or improper operation of the Equipment caused by, resulting from or attributable to (A) abuse, misuse or tampering; (B) alteration, modification or adjustment of the Equipment by other than Seller's authorized representatives; (C) installation, repair or maintenance (other than specified operator maintenance) of the Equipment or related equipment, attachments, peripherals or optional features by other than Seller's authorized representatives; (D) improper or negligent use, application, operation, care, cleaning, storage or handling; (E) fire, water, wind, lightning or other natural causes; (F) adverse environmental conditions, including, without limitation, excessive heat, moisture, corrosive elements, dust or other air contaminants, radio frequency interference, electric power failure, power line voltages beyond those specified for the Equipment, unusual physical, electrical or electromagnetic stress and/or any other condition outside of Seller's environmental specifications; (G) use of the Equipment in combination or connection with other equipment, attachments, supplies or consumables not manufactured or supplied by Seller; or (H) failure to comply with any applicable federal, state or local regulation, requirement or specification governing the equipment and related supplies or consumables.

Repairs or replacements qualifying under this Warranty will be performed on regular business days during Seller's normal working hours within a reasonable time following purchaser's request. All requests for Warranty service must be made during the stated Warranty period. Proof of purchase date is required to make a Warranty request. This Warranty is nontransferable.

Notice: The information contained in this document is subject to change without notice. **Snap-on** makes no warranty with regard to this material. **Snap-on** shall not be liable for errors contained herein or for incidental consequential damages in connection with furnishings, performance, or use of this material. This document contains proprietary information which is protected by copyright and patents. All rights are reserved. No part of this document may be photocopied, reproduced, or translated without prior written consent of **Snap-on**.

Snap-on Equipment, 309 Exchange Ave. Conway, Arkansas 72032 Customer Service and Technical Support Line 800-225-5786

Assembled in USA. Snap-on and Wrench "S" are trademarks of Snap-on Incorporated. ©Snap-on Incorporated 2019. All Rights Reserved. Printed in United States. Snap-on, 2801 80th St., Kenosha, WI 53143 www.snapon.com

Form ZEEWB330B REV C1.. April 2019.. gft

All Rights Reserved